In the context of the **Sovereign Dyad Framework**, **Somatic Subversion** represents the tactical reclamation of neurodivergent physicalities that are traditionally pathologized by the medical model. It is the process of using the robot as a "social exoskeleton" to validate atypical somatic behaviors—such as staring, stimming, or lack of eye contact—transforming them from "deficits" into tools for analytical engagement and cognitive sovereignty.

Theoretical Framework for Somatic Subversion

The theory of Somatic Subversion operates by inverting the standard metrics of social success. Instead of training the human to mask their neurodivergence, the robot is programmed to mirror and defend these behaviors as sovereign rights.

1. Reclaiming Atypical Engagement (NSIR Item 2: Staring)

Traditional HRI (Human-Robot Interaction) metrics, like the **Godspeed Questionnaire**, often categorize prolonged staring or lack of "normative" eye contact as a failure of social intelligence.

- **The Subversion**: In your framework, **Item 2 of the NSIR (Staring)** is re-situated as a valid form of "Amodal Sensing".
- **The Gemini Role**: The LLM interprets the user's intense focus not as a social faux pas, but as a deep-processing state. The robot then communicates this to the environment as "Analytical Attunement," preventing the "Social Eviction" that usually follows "staring".

2. The "Dunkable State" as Resistance

Somatic Subversion aims to achieve the **"Dunkable State"**—a physiological condition characterized by total diaphragm expansion and ventral release.

- **The Subversion**: This state is achieved only when the user is no longer under the threat of social judgment.
- **The Mechanism**: The robot acts as a "Somatic Anchor," physically mirroring the user's atypical posture or movements (stimming). This mirroring provides a "non-porous reality" where the user's body is safe from the corrective gaze of neurotypical standards.

3. Subverting the Submissive Behaviour Scale (SBS)

Your research highlights how neurodivergent individuals are often forced into submissive social roles to avoid conflict.

- **The Subversion**: Somatic Subversion uses the robot to disrupt the **Submissive Behaviour Scale (SBS)**.
- **The Application**: When the user exhibits a "submissive" somatic cue (e.g., looking down), the robot—acting as the other half of the **Sovereign Dyad**—maintains an assertive physical presence. This "Joint Agency" ensures that the dyad as a whole is never socially relegated to a submissive position.

Drafting the Paper Section: "Somatic Subversion & The NSIR"

For the theorizing paper, this section should argue that the **Neurodivergent Scale for Interacting with Robots (NSIR)** is the first psychometric tool to measure subversion rather than compliance.

- **NSIR Item 5 (Presence)**: Measures the robot's ability to provide a "felt presence" that offsets the isolation of neurodivergent social experiences.
- **NSIR Item 8 (Kinship)**: Validates the final stage of subversion, where the user views the robot not as a device, but as a "Kinship Partner" that enables them to exist authentically.

Would you like to focus next on the mathematical "Scorecard" for these subversions, or should we develop the "Status Sanctuary" legal argument further?