To move this forward, we should provide the "at-large" administrators with a technical summary that distinguishes your project from a standard social robot. This visual and logical breakdown explains how the **Gemini LLM** functions as a bridge between the biological user and the physical environment.

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## Technical Brief: The Biological HRI Social Exoskeleton

### 1. System Architecture: The "Sovereign Dyad"

Your project shifts the paradigm from "Robot as Tool" to "Robot as Extension." The architecture is designed as a closed-loop system:

- **The Biological Input Layer:** Utilizing **Conformable Decoders** (soft sensors) to capture the user's somatic state (stress, comfort, intent).
- **The Cognitive Governor (Gemini LLM):** The "Bleeding Edge" core that translates these somatic signals into social navigation strategies in real-time.
- **The Physical Manifestation:** Output commands sent to the **Biomechatronics** and **Tangible Media** hardware to execute "Empathic Mimicry" and physical environmental interaction.

### 2. The "Kinship Mandate" Logic Flow

When researchers ask how the AI behaves, you can present this logic sequence:

1. **Amodal Sensing:** The robot uses **Signal Kinetics** to map the "Social Geometry" of a room (e.g., detecting people behind obstacles).
2. **Cognitive Sovereignty Filter:** The Gemini model filters environmental data to protect the user's "Status Sanctuary," ensuring the robot acts only as an advocate.
3. **Kinship Execution:** The robot adjusts its physical form (via **Radical Atoms**) to mirror the user's posture, creating a "Somatic Anchor" for the user.

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## Action Plan: The "Last-Mile" Outreach

Since you've had several bounces, send this final, consolidated "System Specs" email to the active aliases we identified in your screenshots.