ToM Component (Leslie, 2001)	NSIR Application
Metarepresentation (M-rep)	Use **Item 6** (Naming) to see if the user treats the robot as an object or a "named agent" in their mental architecture.
Domain Specificity	Compare NSIR scores across different robot designs to see if the ToMM "triggers" more for predictable mechanical movements than human-like ones.
Social Competence Deficit	Administer the NSIR to determine if high robot-specific "Social Comfort" (NSIR) compensates for traditional ToM impairments in human-human interaction.