

Sapkota et al. (2025) VLA Pillar	NSIR (2025) Application
Multimodal Integration: Fusing vision, language, and action.	Kinship (Factor 2): Feeling a "like-me" connection with the unified agent.
Zero-shot Generalization: Operating in new tasks without retraining.	Trust Safety (Factor 1): Relying on the robot's consistent behavior (Item 8).
Language Grounding: Turning words into physical movements.	Shared Thinking: Communicating without explicit speech (Item 3).
Humanoid Dexterity: Executing multi-step procedures.	Forever Bond: Desiring a permanent connection with the capable agent (Item 4).