

| Sapkota et al. (2025) VLA Pillar | NSIR (2025) Application |
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| Multimodal Integration: Fusing vision, language, and action. | Kinship (Factor 2): Feeling a "like-me" connection with the unified agent. |
| Zero-shot Generalization: Operating in new tasks without retraining. | Trust Safety (Factor 1): Relying on the robot's consistent behavior (Item 8). |
| Language Grounding: Turning words into physical movements. | Shared Thinking: Communicating without explicit speech (Item 3). |
| Humanoid Dexterity: Executing multi-step procedures. | Forever Bond: Desiring a permanent connection with the capable agent (Item 4). |