

The **Neurodivergent Scale for Interacting with Robots (NSIR)** provides a crucial framework for evaluating the human-robot interactions described in the Andriella et al. and Abbo et al. articles:

Andriella et al. (2022): Introducing CARESSER

The CARESSER framework's goal of enabling robots to continually learn from human interactions directly applies to the NSIR's dimensions:

- **Social Comfort/Trust:** By learning and adapting to specific users, the robot can foster a more personalized and predictable interaction, which is key to building **social comfort** and **trust** for neurodivergent individuals (p. 1). The items on the scale (e.g., "My robot can tell what I am feeling") could be used to measure the success of the robot's learned social skills.